



# QUICK BGA EA-H15

## BGA/SMD Rework Station

### **Operation Manual**

Thank you for purchasing our BGA/SMD Rework System. The system is exclusively designed for reworking and soldering SMD component. Please carefully read this manual before operating the system. Store this manual in a safe, easily accessible place for future reference.

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# 1. Summary

Thank you for using QUICK BGA EA-H15 Rework System. This system, which adopts micro-processor control and infrared sensor technology to do soldering and de-soldering to surface mount components safely and accurately, increases bottom heating power based on the original one. It can also control the whole technical process and record all the information by means of the IR Software, thus meeting the higher technical demands of modern electronic industry. It becomes one of the most valued electronic equipments in this field. QUICK BGAEA-H15 consists of two parts: QUICK IR EA-H15 Infrared Rework System and QUICK PL EA-H15 Precision Placement System.

In order to control the soldering process optimally and get the nondestructive and reproductive PCB temperature, IR EA-H15's heating power is up to 2400W, suitable for all applications, such as large or small PCB as well as lead-free process. The technology of re-flow soldering controlled by closed-loop ensures the precise and smaller technical window, even heat distribution and appropriate peak value of temperature for lead-free soldering.

IR EA-H15 Rework System adopts micro-processor control and infrared sensor technology. It has the precision non-contact infrared temperature sensor for de-soldering parts and the middle wavelength infrared heater. The soldering process is under the monitoring of non-contact infrared sensor and optimum control of process can be achieved at any time. The middle-wavelength infrared heater has a well-proportioned and safe heating and power and flexibility necessary for the system, so it can also deal with some PCBs with big thermal capacity and other high temperature situation (lead-free soldering) easily. The adjustable aperture under the infrared heater can protect the adjacent components (which are sensitive to the temperature) on PCB from being heated. No need for nozzles.

IR EA-H15 works under the "open environment", that is, it can calibrate and test temperature in soldering process. When the melting of solder is found by visual inspection, press down the calibrating button to record the melting temperature of solder. IREA-H15 has 10 types of working modes and programmable temperature controlling can modify the parameters of every working modes. IR system and setting of parameters are operated by outside Keyboard as well as by IR soft.

The use of reflow process camera provides the critical visual information for judging the melting of solder during the whole soldering and desoldering process.

Besides, IR EA-H15 can cool down the PCB efficiently. With the intelligent lead-free digital calibrating soldering station, it is a integrated and perfect soldering equipment for any professional user.

PL EA-H15 precision placement system provides precise alignment control for soldering process of IREA-H15 rework system. The precision fine-adjustment and fine-alignment information provided by RPC ensures the perfect soldering results. PL EA-H15 uses a keyboard to control the operation. The outside keyboards and IR EA-H15 and RPC EA-H15 make a whole set of BGA rework system which becomes a higher-end equipment for reworking on electronic products.

## 2. Product Picture



## 3. The unit is supplied with

Please check whether the following parts are included and intact.

- \* Main Unit BGA EA-H15
- \* Control box
- \* IR Camera—RPC
- \* BGA EA-H15 Operation Manual
- \* video line
- \* USB connect line
- \* video capture card
- \* BGA tool box
- \*computer、LCD(optional)

**Note: The parts will be packed according to the packing list. If you don't purchase the optional part, it will not be in the package. If any part stated above is missed out, please contact with our company or agents immediately.**

## 4. Safety Instructions

Note: For safety of system and operator, please read this manual carefully before operating the unit.  
Please note that the unit is suitable for soldering and de-soldering of electronic components.



Note: Top and bottom IR radiator will be very hot during working, so explosive and combustible object or gas and solvent is strictly prohibited in working areas, also please don't touch the hot housing parts



Note: The laser alignment device includes a secondary laser device, so don't see the laser beam directly.



Note: When the system happens trouble and needs maintenance, it should be carried on by a experienced and authorized technician or expert, or contact with service agent and factory.

The unit with dangerous voltage! The inexperienced work is dangerous for operators.

## 5. Specifications and Technical Parameters

### 5.1 Specifications

#### IR System:

1. General Power: 2400W (max)
2. Power of Bottom Heater: 400W\*4=1600W (Infrared ceramic heating tube)
3. Power of Top Heater: 120W\*6=720W (Infrared heating tube, wavelength 2~8μm, size: 60\*60mm)
4. Preheating Time of Bottom Heater: about 90s, size: 260\*260mm
5. Top heater range size: 20~60mm
6. Heating time of Top Heater: about 10s (room temperature ~230°C)
7. Vacuum Pump: 12V/300mA, 0.05Mpa
8. Top cooling Fan: 24V/300mA 15CFM
9. Laser Alignment Tube: 5V/30mA 2pcs
10. LCD Display Screen: 65.7\*23.5 (mm) 16\*2 character
11. Communication: Standard USB connector (Connect with PC)
12. Movable Motor: stepping motor
13. Movable Arm Range: 128mm
14. Infrared Temperature sensor: 0~300°C (Testing range)
15. Outside K Type Sensor: 3pcs
16. Max PCB Size: 400mm\*400mm
17. Fuse: 3pcs, 20A (220V)

#### PL System:

1. Power: about 15W
2. Camera: 12V/300mA;  
Magnification: 22×10 times  
Horizontal resolution: 480 TV lines  
PAL format (composite)
3. Vacuum Pump: 12V/600mA 0.05Mpa (max)
4. LED lighting: yellow LED below light blue LED up light (with adjustable brightness)
5. Movable Arm Range: 196mm

6. Movable Motor: stepping motor
7. Size 640\*540\*410 (mm)
8. Camera output signal is video signal
9. The operation of Camera on PL and IR alternates according to the movement of PL's telescopic arm. Brightness of IR camera is controlled by keyboard of PL.

Net weight: 55kg  
Packaging dimension: 835\*715\*870 (mm)

Note: When purchasing the equipment, please indicate the working voltage.

## 5.2 Technical Parameters

TL: Melting temperature of solder

T1: Heat preservation starting temperature of reflow soldering

T2: Heat preservation ending temperature of reflow soldering

T3: Peak value temperature of soldering and de-soldering

T0: Valve temperature: The lowest temperature of Bottom Heater when Top Heater heats up. T0<TB

Tir: The set temperature of bottom heater

TB: The real-time temperature of bottom heater

TC: The real-time temperature of top heater

S1: Heating time rising from T1 to T2

S2: Heating time rising from T2 to T3

S3: Heat preservation time of T3

**IR EA-H15 Rework System has ten working modes and its parameter can be changed according to demand. The following eight data can be referred.**

0.	T1=120°C	S1=50s	T2=140°C	S2=45s	T3=195°C	S3=15s	TL=183°C	TB=150°C
	T0=100°C							
1.	T1=130°C	S1=40s	T2=145°C	S2=45s	T3=200°C	S3=15s	TL=183°C	TB=160°C
	T0=150°C							
2.	T1=140°C	S1=30s	T2=150°C	S2=50s	T3=200°C	S3=20s	TL=183°C	TB=160°C
	T0=155°C							
3.	T1=140°C	S1=40s	T2=150°C	S2=50s	T3=195°C	S3=25s	TL=183°C	TB=165°C
	T0=160°C							
4.	T1=160°C	S1=50s	T2=180°C	S2=40s	T3=230°C	S3=15s	TL=217°C	TB=170°C
	T0=150°C							
5.	T1=160°C	S1=40s	T2=175°C	S2=50s	T3=225°C	S3=20s	TL=217°C	TB=180°C
	T0=170°C							
6.	T1=170°C	S1=40s	T2=185°C	S2=50s	T3=228°C	S3=20s	TL=217°C	TB=180°C
	T0=180°C							

7. T1=180°C S1=40s T2=185°C S2=50s T3=228°C S3=25s TL=217°C TB=190°C  
T0=185°C

## 6. Install and Connect System

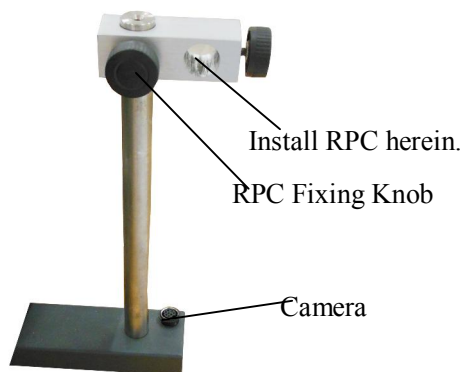
### 6.1 Place System

\* Unwrap the packing of the unit, then take out BGAEA-H15 Main Unit and put it on the horizontal worktable.

\* Make sure whether the unit and parts are in good conditions.

### 6.2 Install RPC

1. Unscrew RPC Fixing Knob on the RPC Fixing Bracket and install RPC in the Bracket , tighten knob.
2. Put the plug of RPC connecting wire into Camera Socket.
3. RPC's position can be adjusted. Unscrew fixing knob in corresponding direction and then adjust. RPC can be moved up and down or turned.



**RPC Fixing Bracket**

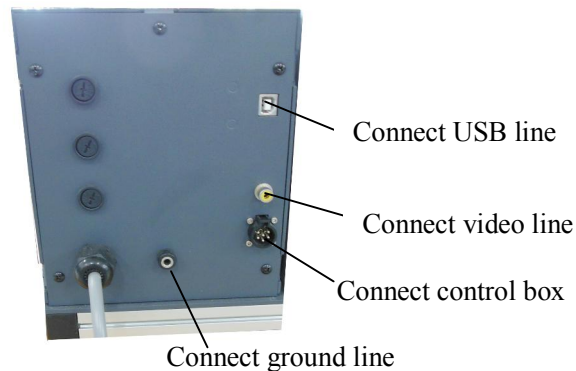


**RPC (Reflow Process Camera)**

### 6.3 System Connecting

- \* \* Please check whether the supply voltage accords with the rated voltage on the system nameplate.
- \* Please check whether all switches are turned off.
- \* Connect the video cord of outside Indicator or Monitor to the VIDEO-OUT socket.
- \* Connect IR camera (RPC) to IR camera socket.
- \* Connect control box to socket.
- \* connect ground line to ground hole.

After all above steps, insert power plug into power sockets, and turn on switch.



## 7. control box Instructions

### IR system Key

- A. During selecting working flow period, UP and DOWN knob are used for controlling the moving upward or downward of cursor but when in standby interface, it can increase or decrease the digital. During the soldering or de-soldering period, also top IR heater haven't started to heat up, knob UP and DOWN are used for controlling movement upward or downward of top IR heater. That is to say, during movement upward and downward of top IR heater, after pressing the key start, UP and DOWN knob make the top heater stop at a proper position.
- B. Under the standby condition, if the cooling fan have already drawn back, press UP and DOWN knob to make the top IR heater move up and down.
- C. Function of OK key: Make the BGA-IR enter parameters setting mode and cursor move a step forward.
- D. Function of "cool/stop" key: if BGA-IR in flow, stop an finish flow; if BGA-IR in flow, open or close cool fan.
- E. Function of "START" key: in standby state, make BGA-IR enter solder and desolder.
- F. Function of "in-out/suck" key: cool fan stretch out or retraction.

### PL system Key

- G. Function of "Z" key: rotate it , can realize suck mouth movable.
- H. Function of "R" key: rotate it , can realize clockwise or anticlockwise rotate, rotate degree have no limit.
- I. Function of "ZOOM/IN-OUT " key: rotate it, adjust magnify ratio of picture, press it, control aligning prism pass in and out.
- J. Function of "FOCUS/SUCK " key: rotate it, realize focus; press it , suck chip.
- K. Function of "BLUE " key: rotate it, adjust blue light of camera; press it, close the light.



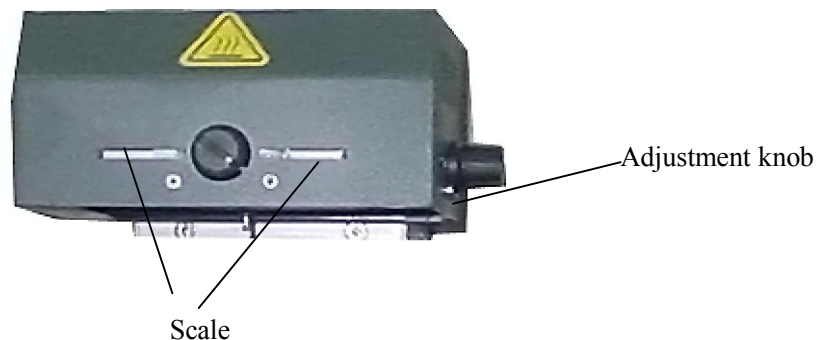
L. Function of “YELLOW ” key: rotate it, adjust yellow light of camera; press it, close the light.

## 8. IR System Operation

### 8.1 Part Function

#### \* Adjust the Aperture System

The Aperture System of Top Radiator can be adjust from 20×20 (mm) to 60×60 (mm) by two Adjustment Knobs. Unscrew the knobs before adjusting, and adjust the window size, then tighten knobs. The scale “2” on the housing means 20mm and “3” means 30mm, other scale is similar. For example, if you want to adjust size to 50×50(mm), adjust two knobs to the scale of “5” and tighten them.



#### Note:

Adjusting the aperture system can protect the adjacent components on the PCB from being heated. But, when the aperture system is adjusted to small size, the Top Radiator will be very hot and decrease its lifetime, so it's necessary to increase the window size appropriately to avoid the damage of the Top Radiator.

### 8.2 Parameters Setting

Parameter settings order as the follows:

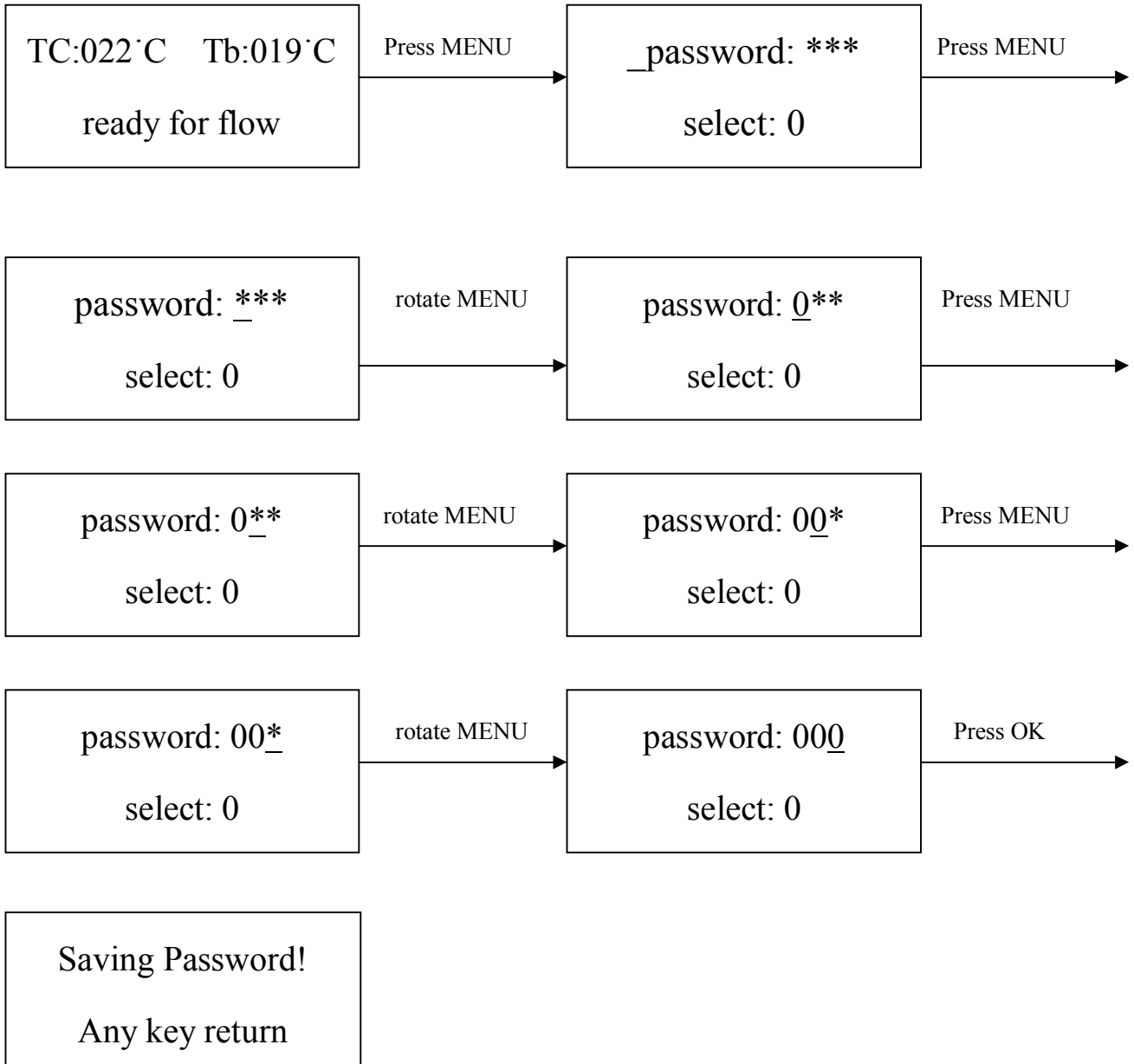
- A. `_password: ***` (Password settings)
- B. `_select: 0` (Flow settings, it can modify parameter inside.)
- C. `_type: solder` (Working mode settings)
- D. `_laser: off` (Laser alignment settings)
- E. `_baud: 19200` (Communication speed settings)

A. Input password

The initial password of system is “000”. At the same time, system also has the omnipotent password “159”. If you forget the setting password, you can input “159” to make the password of system come back to initial password “000”.

**Note:** If want to modify any parameter system, you must input password, otherwise, you can only browse them.

**For instance: Input the initial password “000” of system.**



**After input password:**

1. If you want to modify the password, return to above mode to input the new password. If password is modified successfully, it will show:

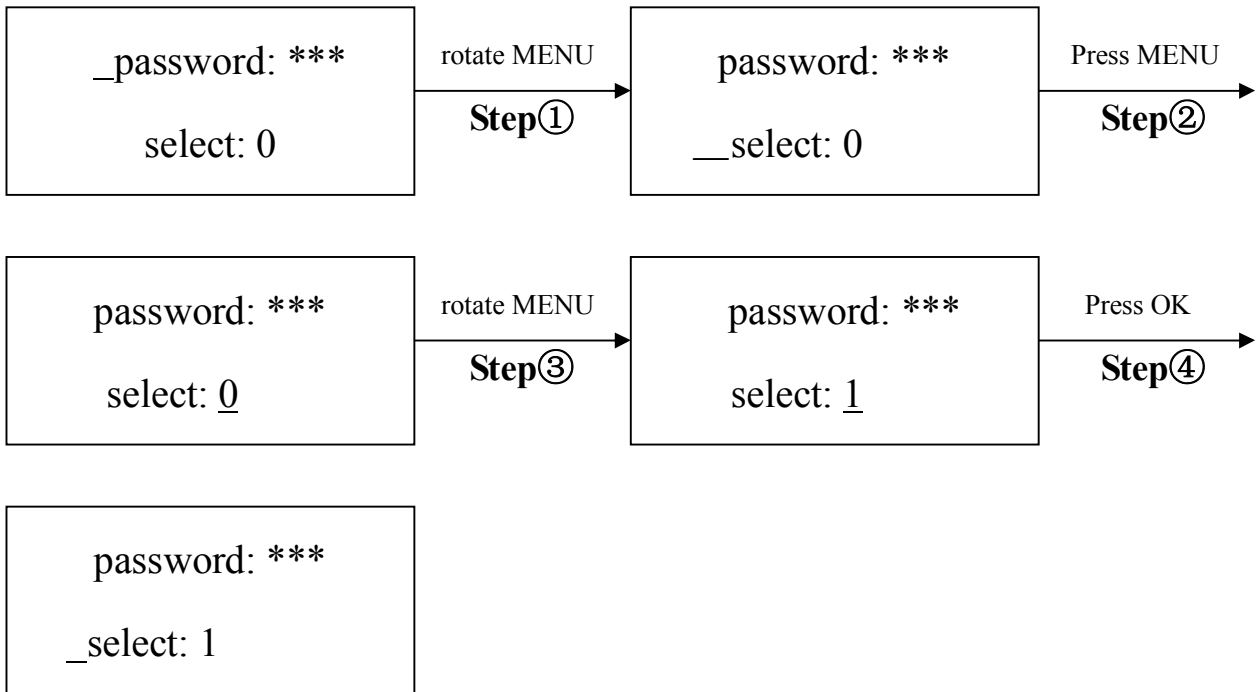
Saving Password !

Any key return !

2. If you want to modify the next working flow, operate as the following B item; If you don't want to modify, please press **DOWN** knob to browse the following parameter settings.

### B. Modify working flow

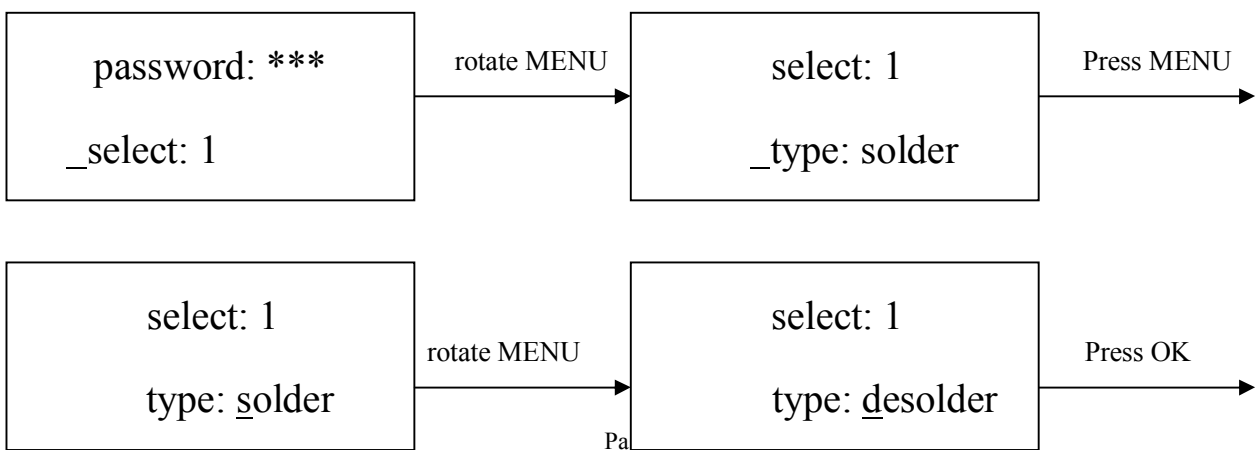
**For instance: Modify the working flow and make it become 1 flow.**



1. When carry on the forth step (**Step④**), if press “SET” key, you can browse and modify parameter of this flow, shown as C-1 item.
2. After finishing modifying of working flow 1, if you want to modify the next working mode, operate as C item shows; If you don't want to modify it, you can press **DOWN** knob to browse the next parameter settings.

### C. Modify working mode

**For instance: Modify the working mode and make it in “desolder” mode.**



```
select: 1
_type: desolder
```

After finishing modifying working mode, if you want to modify laser alignment mode, operate as D item shows; if no need to modify it, please press DOWN key to browse the next parameter settings.

### C-1. Modify Parameter of working flow

1. If it is necessary to modify parameter of a working flow, first you must select the working flow and then modify its parameter.

The soldering technics is decided by T0, TB, T1, T2, T3, S1, S2 and S3. It describes the temperature graph during the system working. TL denotes Melting temperature of solder and the range between T2 and T3.

#### T0

T0 is the valve temperature for bottom heater required by top heater when it heats up. Also it is the first temperature of this technics process. When the work flow begins, the bottom heater starts to heat up. After reaching the T0, the top heater begins to heat up.

#### TB、Tir、TC

TB: The test temperature of bottom preheating Tir: set temperature of bottom heating TC: Real-time temperature of top heating

#### T1

It is the heat preservation starting temperature of reflow soldering. It is the second temperature of this technics process. The temperature rises to T1 with a proper speed the component permits. In parameter modifying, use the UP and DOWN knob to set the value of T1.

#### T2

It is the temperature when finish the heat preservation of reflow soldering. The pre-heating temperature rises to T2, after the time of S1 finishes. Within this time, PCB and component pre-heating is finished and the solder is activated. In parameter modifying, use the UP and DOWN key to set the value of T2.

#### T3

It is the peak value temperature of reflow soldering. When the temperature reaches T2, the temperature equably rises to T3 with a definite raising speed. The soldering or de-soldering will be finished when the temperature reaches to the peak value and performs the next step. In parameter modifying, use the UP and DOWN key to set the value of T3.

**TL**

Melting temperature of solder. At this temperature, the solder starts to melt down and turn into liquid. During the soldering and de-soldering, users can press CAL Key to calibrate the value of TL when the solder turn into liquid. In parameter modifying, use the UP and DOWN knob to set the value of TL.

**S1**

Heating time rising from T1 to T2. User can set the value in the range of 0~300s.

**S2**

Heating time rising from T2 to T3. User can set the value in the range of 0~300s.

**S3**

Prolonged heating time (Heat preservation time) after the temperature reach T3, and user can also set the value in the range of 0~999s.

**Unit**

It's able to set the unit of display temperature during work flow. In parameter modifying, use UP and DOWN keys to set the value of it.

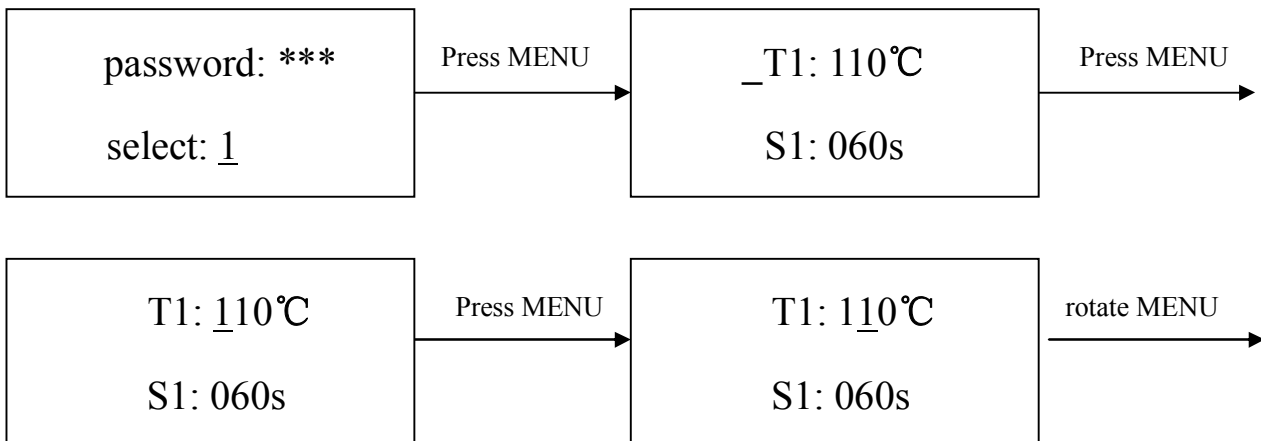
**Sensor**

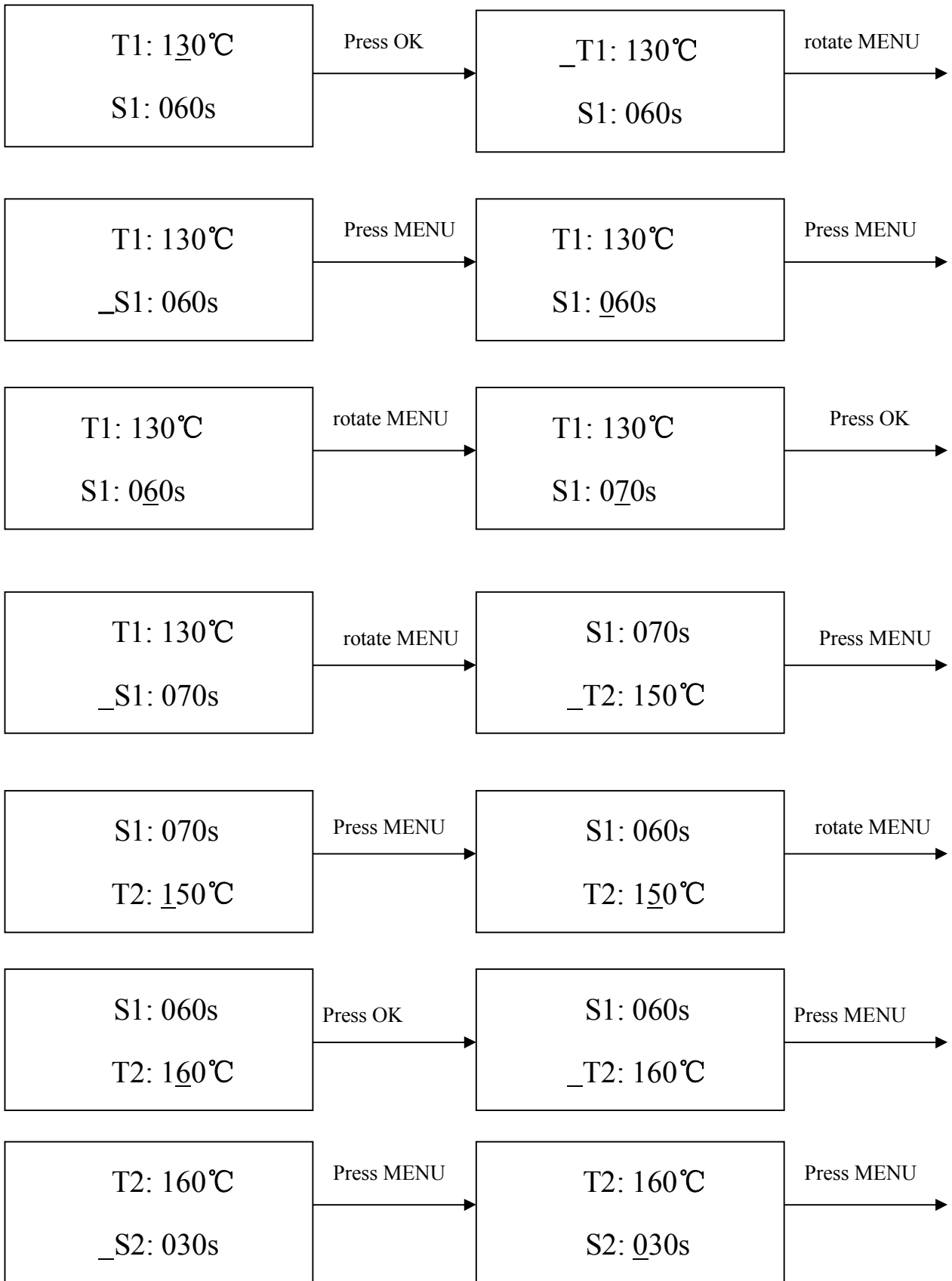
It is used for choosing the system's sensor type. Users can also choose K type sensor used for measuring temperature, besides system's IR sensor. The signal of chosen sensor will be displayed and used for process controlling. In parameter modifying, use the UP and DOWN key to set the value.

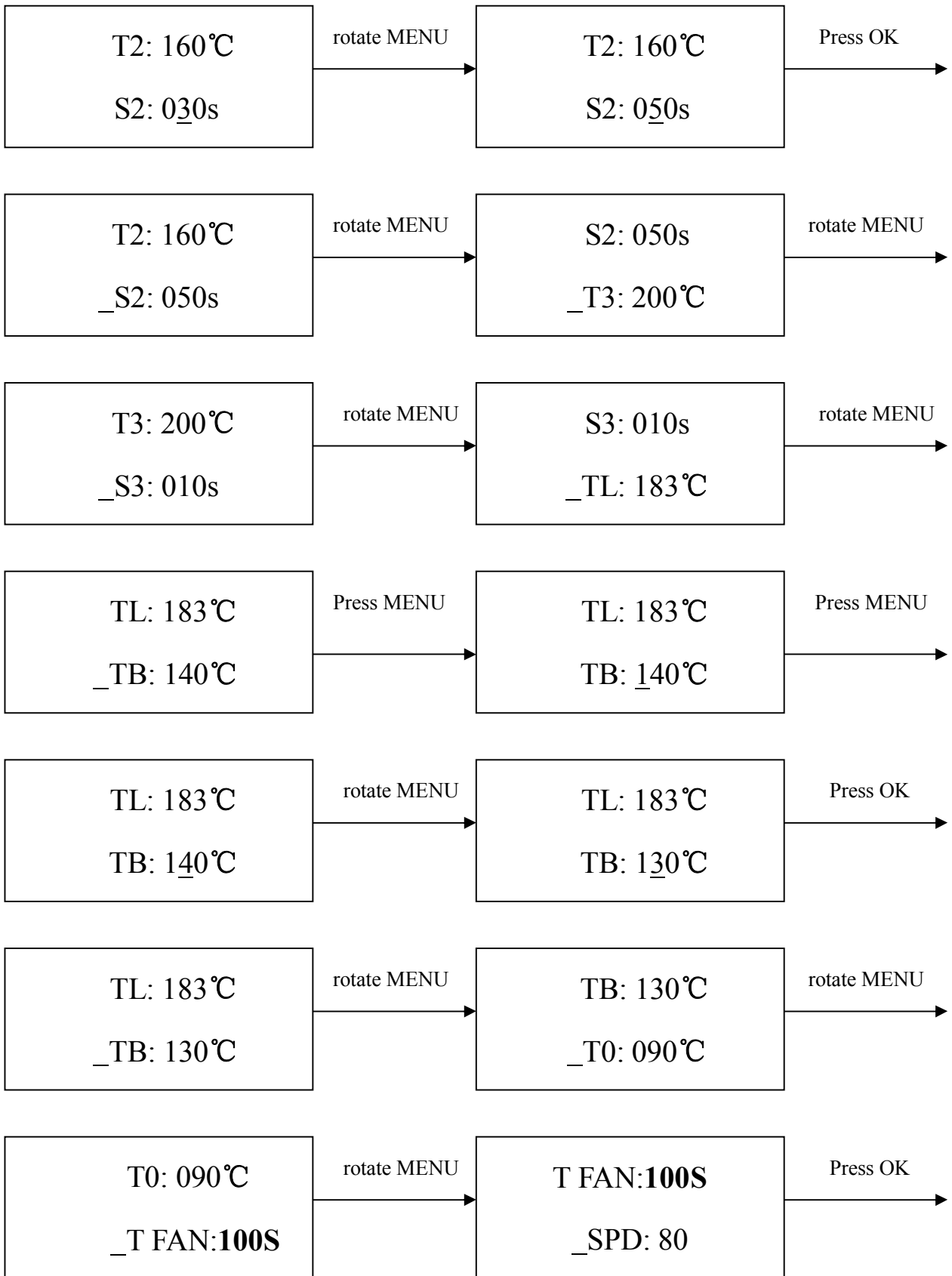
**Password**

It is used for setting password. It is designed for preventing the equipment unnecessary or non-authorized change. When it is set to "000", the password protecting is useless. The password is used for all flows and it can be useful and useless in each flow. The system requires inputting correct password before any change. Using of password refer to A item.

**For instance : Modify parameter of flow one and make T1=130°C, S1=70s, T2=160°C, S2=50s, TB=130°C. (Flow one has been selected)**





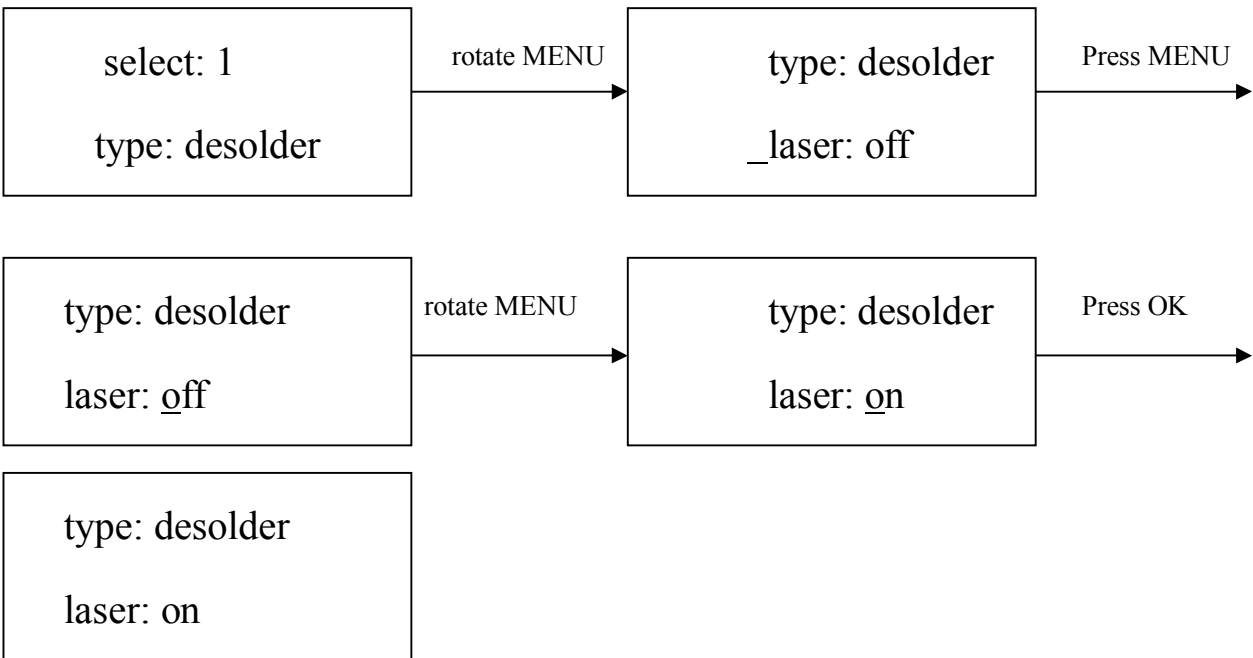


```

TC:022°C  Tb:019°C
ready for flow
    
```

### D. Modify laser alignment mode

For instance: Modify the laser alignment mode and set it to “on”.



1. After finishing the modification, the next step communication speed, will not be able modified by keyboard.
2. Press OK key to exit. Now, the system has saved all parameter settings, IR window will display:

```

TC:022°C  Tb:019°C
ready for flow
    
```

3. After all technics parameters have been selected, press BEGIN key and the system perform the set flow.

### E. System Error Indication

1. In initial state, if the top sensor or outer sensor is broken, it displays:

```

TC: ***°C  Tb: ***°C
T  sense error !
    
```



If the bottom sensor is broken, it displays:

TC: \*\*\*°C    Tb: \*\*\*°C  
B    sense error !

If above status happens, user should stop operating.

2. During the upward or downward movement of Top Heater or holding out and drawing back of fan arm, if it doesn't reach over 10 seconds, the unit will come back to initial state all and singular in spite of what state it is here. It displays:

TC: \*\*\*°C    Tb: \*\*\*°C  
Move error !

3. When TC is less than 180°C during working, if the rising temperature is less than 7°C, and the system will exit the process and display "TC raise error".
4. If TC is over than 265°C during working, the system will exit the process and display "TC over error".

## 8.3 Operating technics instruction



Note: Top and Bottom Heater will be very hot during working, so please don't touch the hot housing parts.



Note: The laser alignment device includes a secondary laser device, so don't see the laser beam directly.

### 8.3.1 Soldering Technics

1. Turn on power switch of each part.
2. Move PCB Fixture with fixed PCB and make it above the Bottom Radiator and make the soldered component on the PCB between Top Radiator and Bottom Radiator. The position is easy to be measured with laser alignment device. The right position should make the red laser point in the center of component.

3. Adjust aperture system, and get a proper window size.
4. Adjust RPC in appropriate place, adjust size and focus of image with PL keyboard to display component image in the monitor clearly.
5. Select parameter with keyboard. (Refer to Parameters setting)
  - A. Input password "000"
  - B. Select the required flow, if need to modify, perform relevant operation.
  - C. Select "solder" working mode.
  - D. Select "IR" laser alignment mode.
  - E. No change to communication speed, and press EXIT key to exit. IR window shows:

TC:022°C Tb:019°C

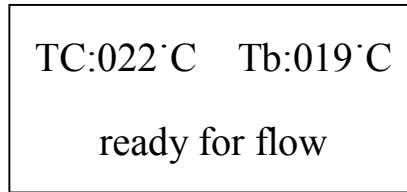
ready for flow

- F. Press "START" key , and the system start working, perform content of selected flow.
6. IR window will display series of setting temperatures and the current temperature of Tb and TC during working, and indicate when it reaches T0, T1, T2, T3 and TL. S1, S2 and S3 are counted down and user can know about the setting value clearly.
  7. If you see the solder has melted down (It is watched with RPC and Monitor), you can press CAL key to calibrate temperature of TL to adjust the display temperature to liquid temperature TL.
  8. When the temperature reaches TL, there will be a voice signal.
  9. When the temperature reaches T3, the sound signal changes to a briefness sound and the system delays heating by S3 seconds. After that, the system will not heat up anymore and exit the process automatically, the technical process is over.
  10. The system can perform a series of function action during working.
    - A. After press START key, the top heater move downwards near to bottom.
    - B. After the system sounds unvaryingly, the top heater move upwards and Top Cooling Fan and Outside Cooling Fan spread out to blow cooling air simultaneously.
    - C. After 150 seconds, the two Cooling Fns stop blowing, and the soldering technics has been finished.

### 8.3.2 De-soldering Technics

1. Turn on power switch of each part.
2. Fix the PCB on the top of Bottom Heater and make the de-soldered component between Top Heater and Bottom Heater. The position is easy to be measured with laser alignment device. The right position should make the red laser point in the center of component and the suction pad in center of component also.
3. Press the vacuum suction tube to check whether suction pad is in the center of component. (If the deflection is too much, the tube will not be able to pick up the component.
4. Adjust aperture system, and get a proper window size.
5. Adjust RPC in appropriate place, adjust size and focus of image with PL keyboard to display component image in the monitor clearly.
6. Select parameter with keyboard. (Refer to Parameters setting)
  - A. Input password "000"

- B. Select the required flow, if need to modify, perform relevant operation.
- C. Select “desolder” working mode.
- D. Select “IR” laser alignment mode.
- E. No change to communication speed, and press OK key to exit. IR window shows:



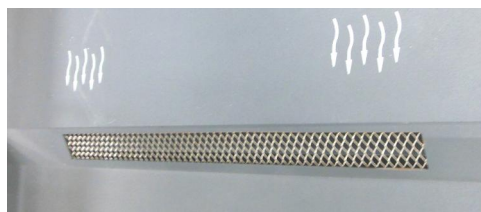
- F. Press START key and the system start working, perform content of selected flow.
7. After pressing START key, Bottom Heater starts to heat up and Top Heater moves downwards and reach to bottom.
  8. IR window will show a series of setting temperatures during working. Indicate when it reaches T0, T1, T2, T3 and TL. When the bottom temperature reaches T0, the top heater begins to heat up.
  9. When the temperature reaches TL, it will give a sound alert automatically (Low frequency).
  10. When the temperature reaches T3, it will also give a sound alert automatically. (Middle frequency)
  11. When the solder has melted down, press the vacuum suction tube to pick up the component.
  12. Press the vacuum suction tube, the vacuum pump start to work and pick up component, then return to original position. The system stops heating.
  13. The Top Heater moves upwards and stops at top.
  14. Top Cooling fan and Outside Cooling Fan spreads out to blow cooling air simultaneously.
  15. 90 seconds after the top heater starts moving upwards, the vacuum suction tube loses component automatically.
  16. After the two Cooling Fans blow cooling air for 150 seconds, the whole de-soldering process will be over.

## 9. PL System Operation

### 9.1 Component function

#### 1. Crosswise Cooling Fan

Besides the existing top cooling system, the system adds outside Cooling Fan again to speed up the cooling process of PCB.

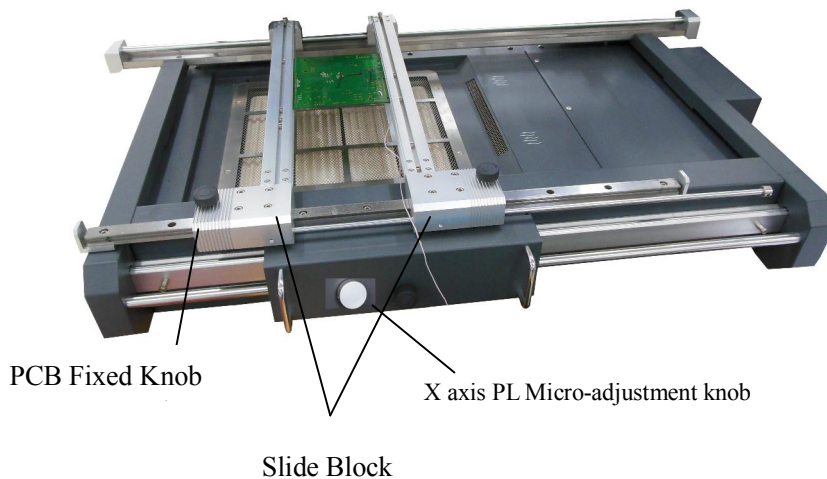


#### 2. PCB fixture

\* The movable PCB fixture is able to fix PCBs of different sizes. It has four Fixing Knobs and two

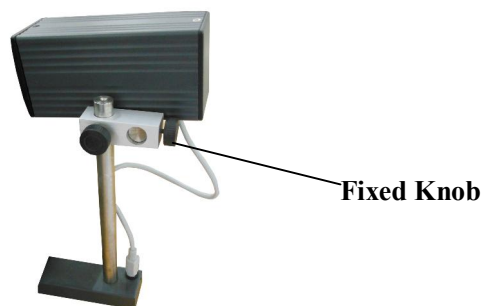
Micro-adjustment Knobs. Two PCB Fixing Knobs are used for locking PCB Clamp Bar to fix PCB. The other two Fixture Fixing Knobs are used for locking the PCB Fixture to prevent it from moving lengthways and transverse. The two Micro-adjustment Knobs are used for adjusting accurately while aligning the component.

- \* Unscrew PCB Fixing Knobs and move the Slide Block to open the PCB Clamp Bar, make the distance in accordance with PCB size. Fix PCB between Clamp Bars and screw down PCB Fixing Knob after adjusting position. If you want to lock PCB Fixture, please screw down Fixture Fixed Knob.
- \* When the component is aligned accurately, screw down Fixture Fixing Knobs first and then adjust accurately. Turn “PL Micro-adjustment knob1 to make PCB Fixture move right and left for adjusting PCB’s right and left position. Turn it clockwise for rightwards move and turn it anticlockwise for leftwards move. Turn “PL Micro-adjustment knob2 to make PCB Fixture move forward and backward for adjusting PCB’s front and rear position. Turn it clockwise for forward move and turn it anticlockwise for move backward.



#### 4.RPC (Reflow Process Camera)

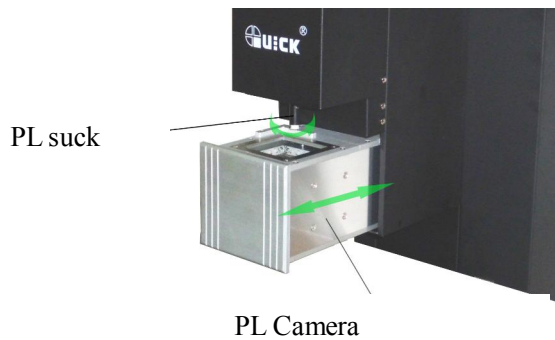
RPC’s position can be adjusted. First, unscrew Fixed Knob in corresponding direction and then adjust. RPC can be moved up and down or turned.



#### 5.PL Camera

- \* It needs to use PL camera during the component aligning. PL camera will transmit the image of soldering point on PCB and component pins under nozzle to Display or Monitor through video signal and user can see these images on Display or Monitor. At the moment, you can use each adjusting function to align component.
- \* It needs to completely pull out PL camera when using it. At this time, the image displayed is got by PL

camera. When not in use, push it back, and the image displayed is got by IR camera.



## 9.2 Aligning Technics

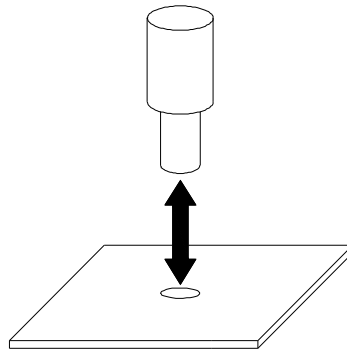
1. Place the soldered component in jig, move PCB Fixture to make the vacuum pen aim at component on the jig. Turn the Nozzle Controlling Knob to make nozzle move down to pick up component. The component should be picked up from its center. As soon as the vacuum nozzle touches component, the vacuum pump starts to work and pick up component.
2. Press Sucks key, prism auto judge stick out or not. Follow flow auto process.  
PL-HEAD (suck) down → auto suck chip → PL-HEAD (suck) upward → prism auto stick out → manual aligning (see follow step) .
3. Watch LCD picture satisfy our require or not, can adjust by keyboard, specific adjust refer to “control box instruction”.
4. Unscrew the PCB Fixing Knobs on the PCB Fixture to open PCB Clamp Bar. Fix the soldered PCB on the PCB Fixture and adjust PCB’s position. Make the Monitor display the image of soldering point, and make the images of soldering point and component in the same position. It is convenient for adjusting. After roughly adjusting, screw down Fixture Fixing Knob to lock PCB Fixture to prevent it from sliding right and left.
5. Align the component with two Adjustment Knobs and two Micro-adjustment Knobs. Make the images of component solder pins and the soldering point on PCB overlap.
6. Press Sucks key, auto place.
7. Align the component with two Adjustment Knobs and two Micro-adjustment Knobs. Make the images of component solder pins and the soldering point on PCB overlap.

## 10. Calibrating the system

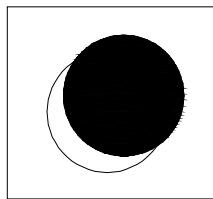
Due to vibrations during transporting, it is necessary to calibrate the system before using. The steps are shown as follows.

1. Insert the calibration plate into the PCB fixture and adjust the position, lock the fixture.
2. The vacuum tube section of vacuum pump will be treated as the calibration hole. (If it has nozzle, please remove it.)
3. Press DOWN key to make PL-HEAD move down.
4. Turn “Nozzle Controlling Knob” to lower the calibration tube. Check whether the calibration tube superposes exactly with the round hole on the calibration plate. If they aren’t superposition, please adjust Micro-adjustment Knobs of fixture until the calibration tube and hole completely superpose. After

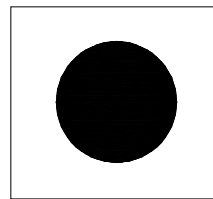
superposing, please don't do any change to the calibration plate or calibration tube.



5. Press UP key to make PL-HEAD move up.
6. Pull out PL Camera and adjust the image displayed by Keyboard. Observe the images: if the two images (Circle) in the Monitor superpose, the system is precise. If not, the system is imprecise, it needs to be adjusted.



Imprecision



Precision

## 11、 Equipment Maintenance

### Remark:

For ensuring reliable function and maintenance of equipment, please use parts provided by original factory. Please turn off power switch of each part and pull out power plug when not in use.



### Note:

After cutting off the power supply, the housing is still very hot, so please don't use any dangerous or combustible solvent to clean it.

### Clean parts:

Clean the dust on system with clean towel.

Suggest to use dry or wet towel to clean the equipment. Solder on the glass of Bottom Radiator can be cleaned out with hard object. Please be careful not to break down the glass.

Clean the prism of PL camera with pledget and be careful not to scrape it.

Use the towel with cleaning oil to clean PCB fixture and orbit.

### Replace Suction Pad:

If you want to replace the Suction Pad of IR System, please turn off power, and replace it after waiting for

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vacuum suction nozzle and Top Heater to cool down.

Take Suction Pad out of suction nozzle downwards, and install a new one in opposite direction.

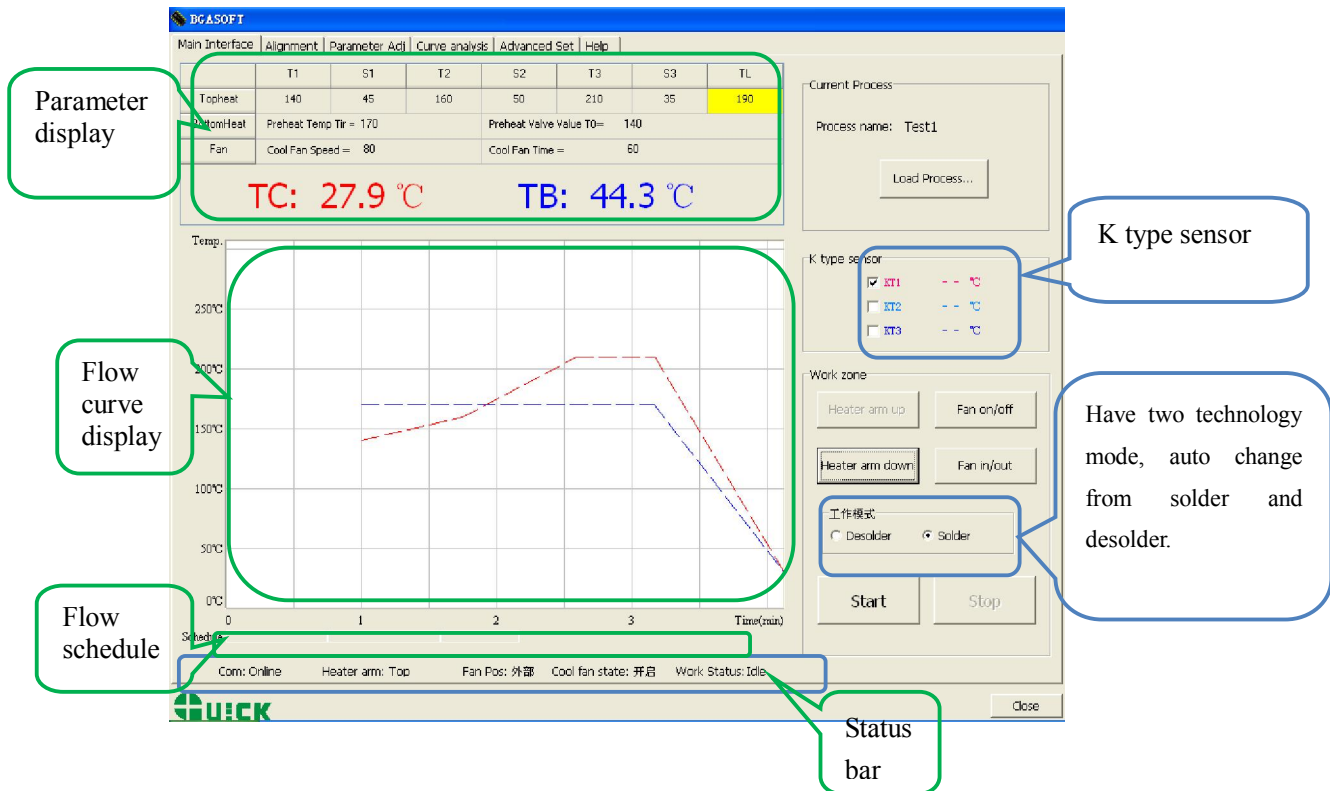
**Note:**

PL EA-H15 is a precise equipment. Please don't make any changes to it. Otherwise the precision of this equipment will be affected.

## 12、QUICKSOFT brief instruction

### 12.1 operation interface

1. Operation interface: this interface reaction executive condition of flow , we can real-time operate by this interface.
2. parameter of operation interface, be setting from “parameter testing interface”, in operation interface do not need setting.



Parameter display: the parameter of this area do not be setting in “operation interface”, it can be setting in parameter debug interface.

Flow select: express technology flow file which parameter have be edit.

K type sensor: KT1~KT3, only connect K type temperature sensor, can display temperature .

Flow curve display window: temperature curve of KT1 – KT3, easy to real-time watch and curve analysis.

Flow status bar: this bar display flow status by colour, colour is corresponding to working colour .

Status bar: real-time display current state, contain “communicate state (online/offline)”, the location of heat head(up/middle/down) , aligning arm location (external/middle/interior) , head dissipation (open/close) ,vacuum state (open/close) .

Only when communicate state is online, we can control equipment auto carry out flow by software.

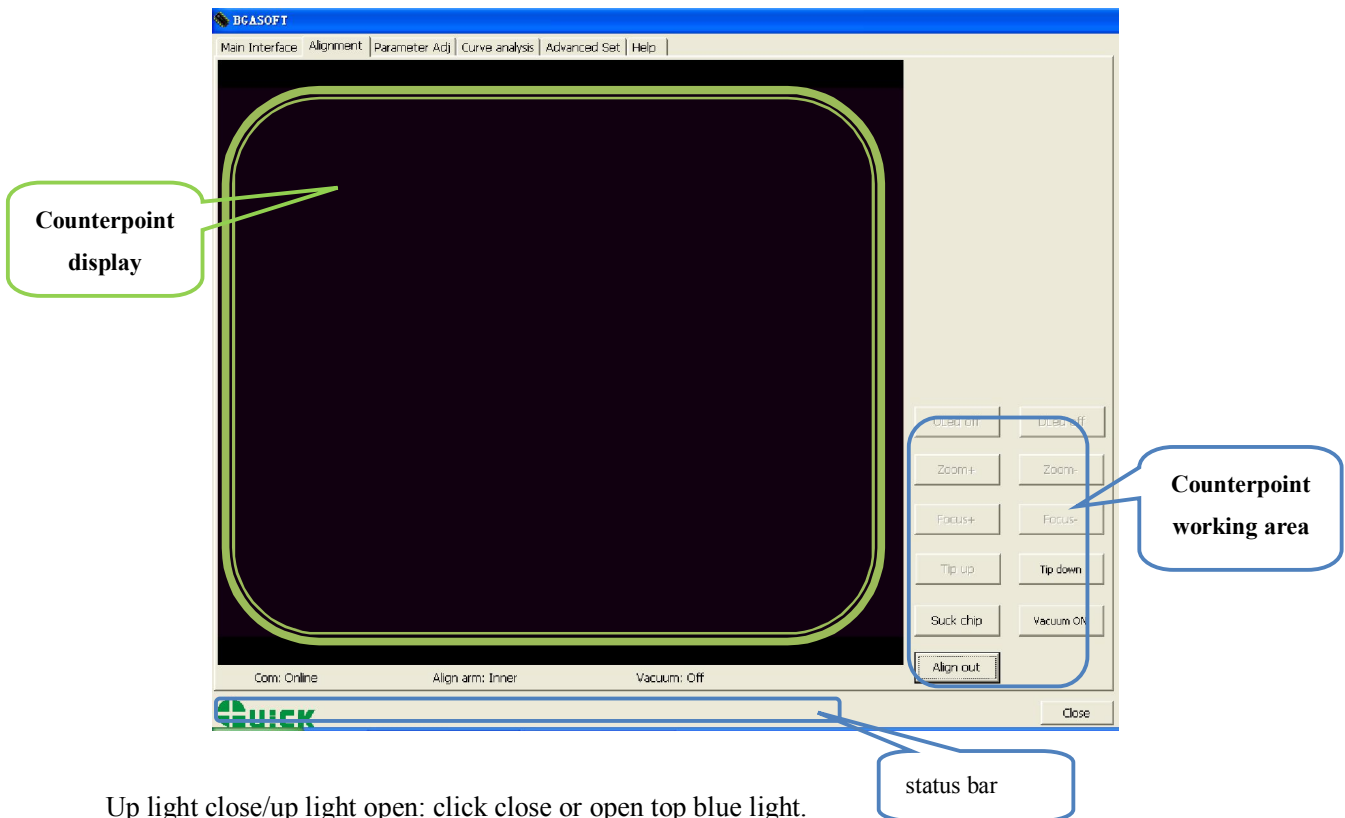
Working area: contain every working button “heat arm up”, “heat arm down”, “dissipation open/dissipation



close”, “cooling fan enter ” , “cooling fan out”.

## 12.2 counterpoint operation interface

We can complete total counterpoint operation by counterpoint operation interface , contain focus, magnify reduce, suck component, etc.



Up light close/up light open: click close or open top blue light.

Down light close/down light open: click close or open top yellow light.

Amplification: amplify picture of display window.

Reduction: reduce picture of display window.

focus+: magnify picture focus.

focus-: reduce picture focus.

Heat arm up: click, heat arm move up; press on continuous, heat arm move up continuous.

Heat arm down: click, heat arm down; press on continuous, heat arm move down continuous.

Suck component /place component: click , then suck component.; after suck, show “place component”, and then click this button, place component, button display change to “suck component”.

Vacuum open/vacuum close: open or close vacuum pump.

Aligning arm in / out: click, can make aligning arm which in external retraction , the location state change to “interior”; again click aligning arm, it will move to external ,the location state change to “external”.

Exit : exit “counterpoint operation ”interface, enter “operation interface”, current state have no change.

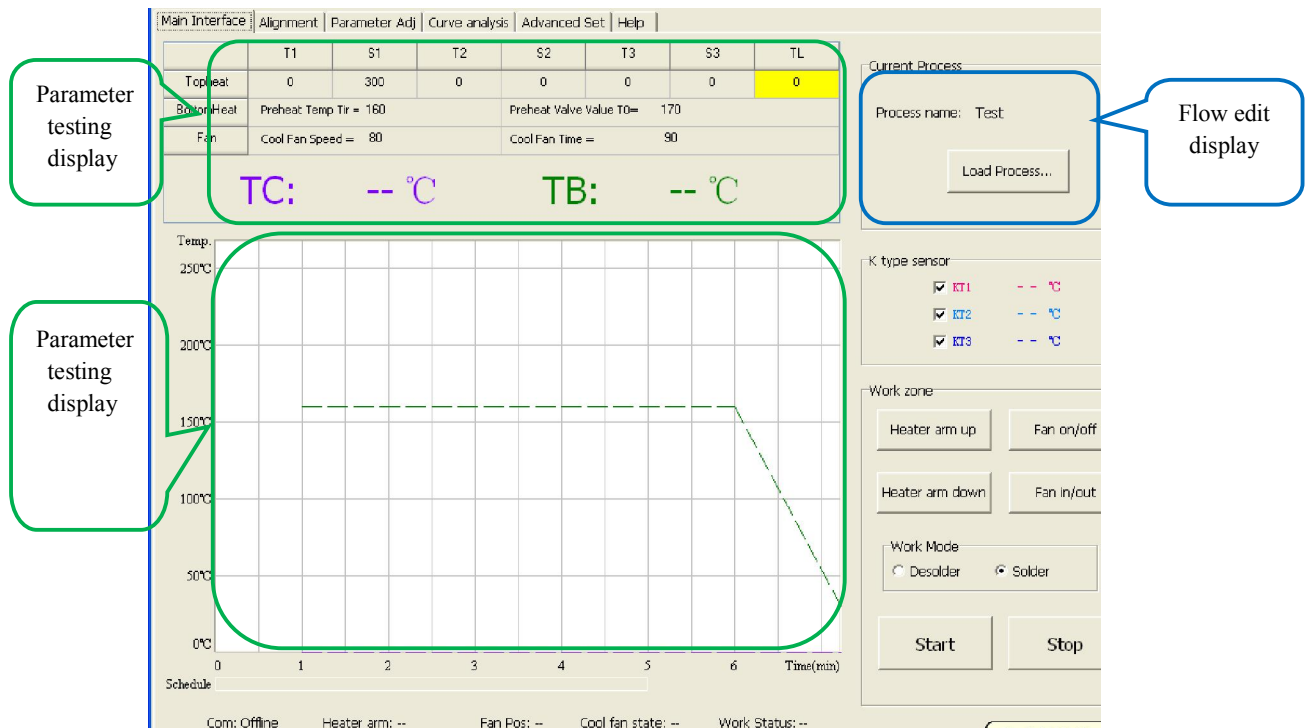
When working area display aligning arm in, then status bar location of aligning arm: external;

When working area display vacuum open, then vacuum state in status : “close”.

When status bar display “high speed mode”, express move speed is high, When status bar display “low speed mode”, express move speed is low. This function effect in counterpoint interface.

## 12.3 parameter testing interface

Parameter testing interface: when solder or desolder new chip, by this display ,we can do solder or desolder testing.



	T1	S1	T2	S2	T3	S3	TL
Top heat	0	300	0	0	0	0	0
Bottom Heat	Preheat Temp Tir = 160			Preheat Valve Value T0= 170			
Fan	Cool Fan Speed = 80			Cool Fan Time = 90			

TC: -- °C      TB: -- °C

Temp. (°C): 0, 50, 100, 150, 200, 250

Time (min): 0, 1, 2, 3, 4, 5, 6

Current Process: Test

Process name: Test

Load Process...

K type sensor:

- RT1 -- °C
- RT2 -- °C
- RT3 -- °C

Work zone:

Heater arm up      Fan on/off

Heater arm down      Fan in/out

Work Mode:

Desolder       Solder

Start      Stop

Com: Offline      Heater arm: --      Fan Pos: --      Cool fan state: --      Work Status: --

Counterpoint height: memory setting height. After setting, auto memory this height, the same specification chip counterpoint, call save flow, do not need adjust counterpoint height.

Counterpoint height cancel: cancel saved counterpoint height.

Suck height: memory sucking height which have be set. After setting, auto memory this height, when suck the same chip next time, we can call the saved flow, not need adjust counterpoint height.

Cancel suck height: cancel suck height which have be saved.

In flow edit display, show goal flow name and technology type (desolder/solder)、nozzle size、down distance and heat dissipation air quantity etc.

Down distance: adjust heat head height range, setting range 0~255mm; heat dissipation air quantity setting range 35~100. (can adjust on the basis of PCB adjust)

After edit parameter in parameter setting display, in“flow edit display”input flow name, appropriate nozzle size, select flow technology curve is “desolder”、or “solder”. And then click “parameter save”、“save curve”, can save current parameter and flow curve.

In parameter setting display, can set parameter, setting range refer to 5.1.

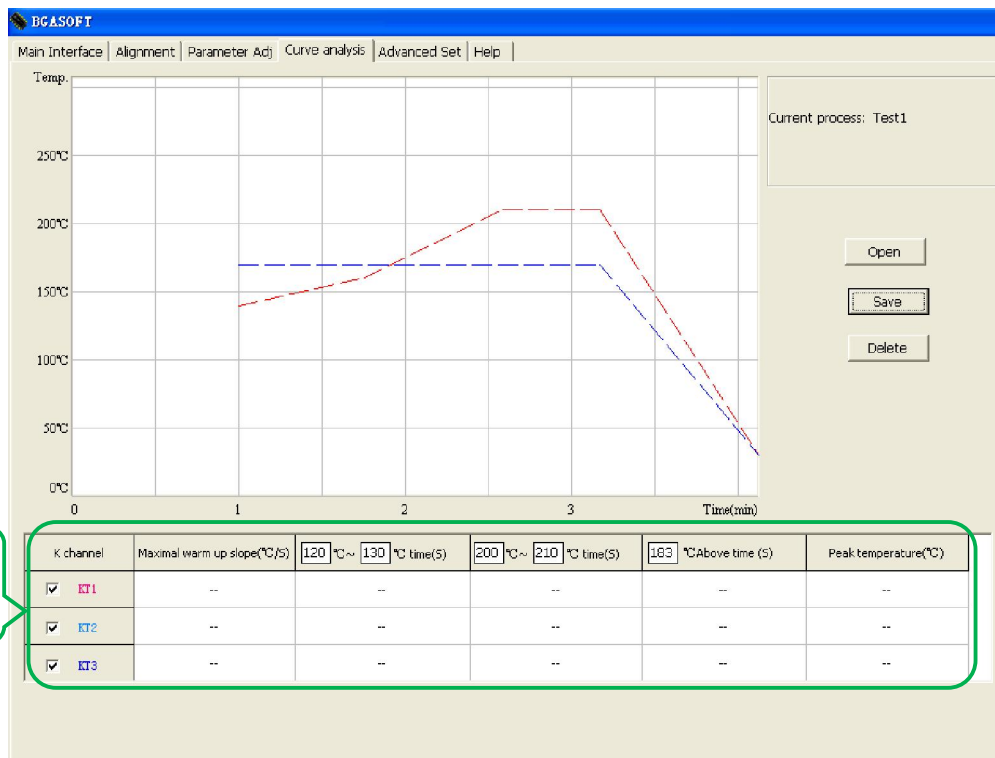
T0: only satisfy “ $TIR \geq T0$ ”, top infrared heater can start working. No special purpose, please set  $Tir > T0$ .

Can also click “flow select” in “edit flow display”, call saved parameter and modify it. heat dissipation air quantity : 35~100.

Note: parameter setting please refer to technology require.

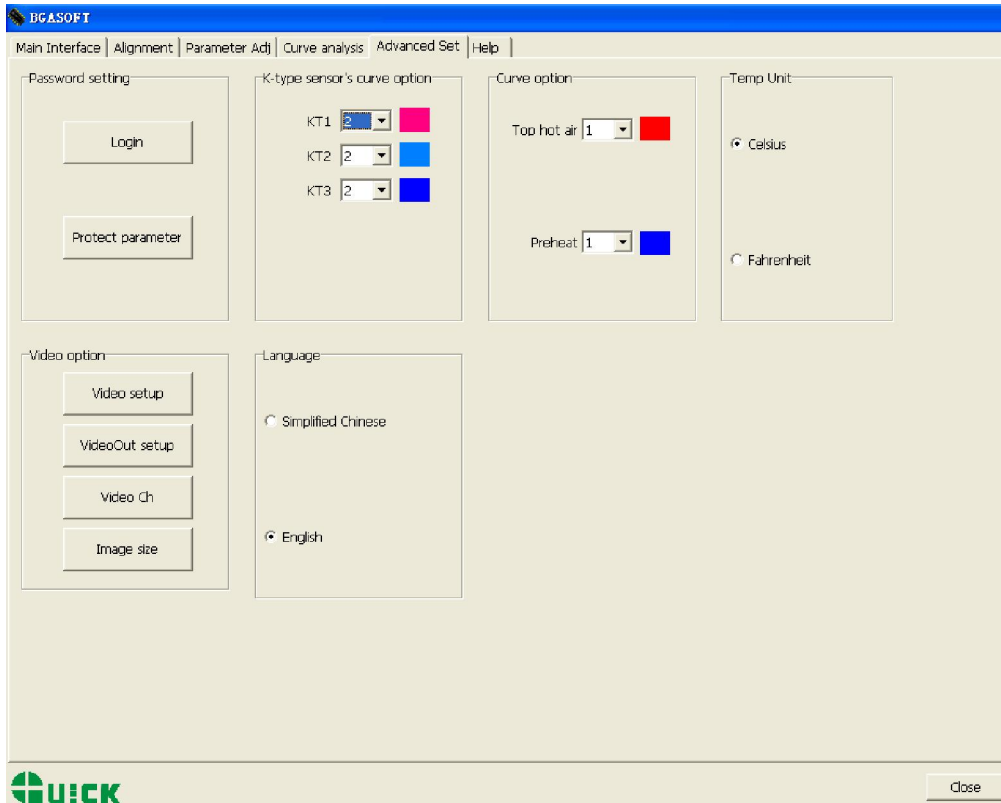
## 12.4 curve analysis interface

1. Curve analysis display: this display can analysis KT1—KT3 flow curve, know peak temperature of this flow, temperature rise slope, temperature change of every heat process and time, thus judge if correspond technology flow.
2. In curve analysis interface, can save or delete current curve, or call saved curve analysis, and also print current curve file.
3. After open flow file , flow curve interface auto display flow curve; if flow file contain external K type temperature test data, then display temperature arise time, maximum temperature rise slope, peak temperature.



## 12.5 advanced setting interface

Advanced setting: in this interface, we can set operation limits of authority, communicate video etc. and also can set T0, temperature curve colour and wire wide, and can select china and English.



Password setting: can set “enter password” and “parameter protect” two type password.  
 The people who obtain enter password can operation this software, but no parameter modify power.  
 The people who obtain parameter protect can operation this software, and modify parameter.  
 If not set parameter protect password, people who obtain enter password also modify parameter.

Language version select: can select language china or English.  
 Select Chinese, then software interface is Chinese.  
 Select English, then software interface is English.

Colour of K type temperature curve setting: provide different colour and curve wide. In technology interface, temperature display by curve, different colour express different K type temperature sensor.

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